Product datasheet

Specifications



variable speed drive, Altivar Machine ATV340, 4kW, heavy duty, 400V, 3 phases, Ethernet

ATV340U40N4E

Main

Range of product	Altivar Machine ATV340
Product or component type	Variable speed drive
Product specific application	Machine
Mounting mode	Cabinet mount
Variant	Standard version
Communication port protocol	EtherNet/IP Modbus serial Modbus TCP
Network number of phases	3 phases
Supply frequency	50...60 Hz +/- 5 %
[Us] rated supply voltage	380...480 V - 15...10 %
nominal output current	9.3 A
Motor power kW	5.5 kW for normal duty 4 kW for heavy duty
Motor power hp	7 hp for normal duty 5 hp for heavy duty
EMC filter	Class C3 EMC filter integrated
IP degree of protection	IP20

Complementary

Discrete input number	5
Discrete input type	PTI programmable as pulse input: 0…30 kHz, 24 V DC (30 V) DI1...DI5 safe torque off, 24 V DC (30 V), impedance: 3.5 kOhm programmable
number of preset speeds	16 preset speeds
Discrete output number	2.0
Discrete output type	Programmable output DQ1, DQ2 30 V DC 100 mA
Analogue input number	2
Analogue input type	AI1 software-configurable current: 0...20 mA, impedance: 250 Ohm, resolution 12 bits AI1 software-configurable temperature probe or water level sensor AI1 software-configurable voltage: 0...10 V DC, impedance: 31.5 kOhm, resolution 12 bits AI2 software-configurable voltage: - 10...10 V DC, impedance: 31.5 kOhm, resolution 12 bits
Analogue output number	1

Disclaimer: This documentation is not intended as a substitute for and is not to be used for determining suitability or reliability of these products for specific user applications

Analogue output type	Software-configurable voltage AQ1: 0...10 V DC impedance 470 Ohm, resolution 10 bits Software-configurable current AQ1: 0...20 mA impedance 500 Ohm, resolution 10 bits
Relay output number	2
Output voltage	<= power supply voltage
Relay output type	Relay outputs R1A Relay outputs R1C electrical durability 100000 cycles Relay outputs R2A Relay outputs R2C electrical durability 100000 cycles
Maximum switching current	Relay output R1C on resistive load, cos phi = 1: 3 A at 250 V AC Relay output R1C on resistive load, cos phi = 1: 3 A at 30 V DC Relay output R1C on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 250 V AC Relay output R1C on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 30 V DC Relay output R2C on resistive load, cos phi = 1: 5 A at 250 V AC Relay output R2C on resistive load, cos phi = 1: 5 A at 30 V DC Relay output R2C on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 250 V AC Relay output R2C on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 30 V DC
Minimum switching current	Relay output R1B: 5 mA at 24 V DC Relay output R2C: 5 mA at 24 V DC
Physical interface	2-wire RS 485
Connector type	3 RJ45
Method of access	Slave Modbus RTU Slave Modbus TCP
Transmission rate	4.8 kbit/s 9.6 kbit/s 19.2 kbit/s 38.4 kbit/s
Transmission frame	RTU
Number of addresses	1…247
Data format	8 bits, configurable odd, even or no parity
Type of polarization	No impedance
4 quadrant operation possible	True
Asynchronous motor control profile	Constant torque standard Variable torque standard Optimized torque mode
Synchronous motor control profile	Permanent magnet motor Reluctance motor
Pollution degree	2 conforming to IEC 61800-5-1
Maximum output frequency	0.599 kHz
Acceleration and deceleration ramps	Linear adjustable separately from 0.01...9999 s S, U or customized
Motor slip compensation	Not available in permanent magnet motor law Adjustable Automatic whatever the load Can be suppressed
Switching frequency	2...16 kHz adjustable 4...16 kHz with derating factor
Nominal switching frequency	4 kHz
Braking to standstill	By DC injection
Brake chopper integrated	True
Line current	11.4 A at 380 V (normal duty) 9.0 A at 480 V (normal duty) 13.4 A at 380 V (heavy duty) 10.6 A at 480 V (heavy duty)

Line current	13.4 A at 380 V without line choke (heavy duty) 10.6 A at 480 V without line choke (heavy duty) 11.4 A at 380 V with external line choke (normal duty) 9 A at 480 V with external line choke (normal duty) 8.5 A at 380 V with external line choke (heavy duty) 6.8 A at 480 V with external line choke (heavy duty)
Maximum input current	13.4 A
Maximum output voltage	480 V
Apparent power	9 kVA at 480 V (normal duty) 8.8 kVA at 480 V (heavy duty)
Maximum transient current	14 A during 60 s (normal duty) 14 A during 60 s (heavy duty) 17.1 A during 2 s (normal duty) 16.7 A during 2 s (heavy duty)
Electrical connection	Screw terminal, clamping capacity: 1.5...4 mm² for line side Screw terminal, clamping capacity: 4...6 mm² for DC bus Screw terminal, clamping capacity: 1.5...4 mm² for motor Screw terminal, clamping capacity: 0.2...2.5 mm² for control
Prospective line Isc	5 kA
Base load current at high overload	9.3 A
Base load current at low overload	12.7 A
Power dissipation in W	Natural convection: 99 W at 380 V, switching frequency 4 kHz (heavy duty) Forced convection: 99 W at 380 V, switching frequency 4 kHz (heavy duty) Natural convection: 130 W at 380 V, switching frequency 4 kHz (normal duty) Forced convection: 130 W at 380 V, switching frequency 4 kHz (normal duty)
Electrical connection	Line side: screw terminal 1.5...4 mm²/AWG 14...AWG 12 DC bus: screw terminal 4...6 mm²/AWG 12...AWG 10 Motor: screw terminal 1.5...4 mm²/AWG 14...AWG 12 Control: screw terminal 0.2...2.5 mm²/AWG 24...AWG 12
With safety function Safely Limited Speed (SLS)	True
With safety function Safe brake management (SBC/SBT)	True
With safety function Safe Operating Stop (SOS)	False
With safety function Safe Position (SP)	False
With safety function Safe programmable logic	False
With safety function Safe Speed Monitor (SSM)	False
With safety function Safe Stop 1 (SS1)	True
With sft fct Safe Stop 2 (SS2)	False
With safety function Safe torque off (STO)	True
With safety function Safely Limited Position (SLP)	False
With safety function Safe Direction (SDI)	False

Protection type	Thermal protection: motor Safe torque off: motor Motor phase loss: motor Thermal protection: drive Safe torque off: drive Overheating: drive Overcurrent: drive Output overcurrent between motor phase and earth: drive Output overcurrent between motor phases: drive Short-circuit between motor phase and earth: drive Short-circuit between motor phases: drive Motor phase loss: drive DC Bus overvoltage: drive Line supply overvoltage: drive Line supply undervoltage: drive Input supply loss: drive Exceeding limit speed: drive Break on the control circuit: drive
Width	85.0 mm
Height	270.0 mm
Depth	232.5 mm
Product weight	2.3 kg
Continuous output current	12.7 A at 4 kHz for normal duty 9.3 A at 4 kHz for heavy duty

Environment

Operating altitude	<= 3000 m with current derating above 1000m
Operating position	Vertical +/- 10 degree
Product certifications	UL CSA TÜV EAC CTick
Marking	CE
Standards	IEC 61800-3 IEC 61800-5-1 IEC 60721-3 IEC 61508 IEC 13849-1 UL 618000-5-1 UL 508C
Assembly style	With heat sink
Electromagnetic compatibility	Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 1.2/50 µs - 8/20 µs surge immunity test level 3 conforming to IEC 61000-4-5 Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6
Environmental class (during operation)	Class 3C3 according to IEC 60721-3-3 Class 3S3 according to IEC 60721-3-3
Maximum acceleration under shock impact (during operation)	70 m/s² at 22 ms
Maximum acceleration under vibrational stress (during operation)	5 m/s² at 9...200 Hz
Maximum deflection under vibratory load (during operation)	1.5 mm at 2...9 Hz
Permitted relative humidity (during operation)	Class 3K5 according to EN 60721-3
Volume of cooling air	19.0 m3/h
Type of cooling	Forced convection
Overvoltage category	Class III

Regulation loop	Adjustable PID regulator
Noise level	49.5 dB
Pollution degree	2
Ambient air transport temperature	-40…70 °C
Ambient air temperature for operation	-15…50 °C without derating (vertical position) 50…60 °C with derating factor (vertical position)
Ambient air temperature for storage	-40…70 °C
Isolation	Between power and control terminals

Packing Units

Unit Type of Package 1	PCE
Number of Units in Package 1	1
Package 1 Height	10.700 cm
Package 1 Width	37.200 cm
Package 1 Length	31.800 cm
Package 1 Weight	2.979 kg
Unit Type of Package 2	S06
Number of Units in Package 2	14
Package 2 Height	75.000 cm
Package 2 Width	60.000 cm
Package 2 Length	80.000 cm
Package 2 Weight	55.140 kg

Contractual warranty

Warranty (in months)	18

Environmental Data

Schneider Electric aims to achieve Net Zero status by 2050 through supply chain partnerships, lower impact materials, and circularity via our ongoing “Use Better, Use Longer, Use Again” campaign to extend product lifetimes and recyclability.

Environmental Data explained >

How we assess product sustainability >

Environmental footprint

Total lifecycle Carbon footprint	**3 163 kg CO2 eq.**
Carbon footprint of the manufacturing phase [A1 to A3]	**82 kg CO2 eq.**
Carbon footprint of the distribution phase [A4]	**0.6 kg CO2 eq.**
Carbon footprint of the installation phase [A5]	**0.8 kg CO2 eq.**
Carbon footprint of the use phase [B2, B3, B4, B6]	**3 073 kg CO2 eq.**
Carbon footprint of the end-of-life phase [C1 to C4]	**5 kg CO2 eq.**
Environmental Disclosure	Product Environmental Profile

Use Better

Materials and Substances

Packaging made with recycled cardboard	**Yes**
Packaging without single use plastic	**Yes**
SCIP Number	**81d6792e-d307-4115-9475-2db3f34c93af**
EU RoHS Directive	Compliant By Exemption
REACh Regulation	Reference contains Substances of Very High Concern above the threshold

Energy efficiency

Product contributes to saved and avoided emissions	**Yes**

Use Longer

Lifetime extension

Repair	**No**

Use Again

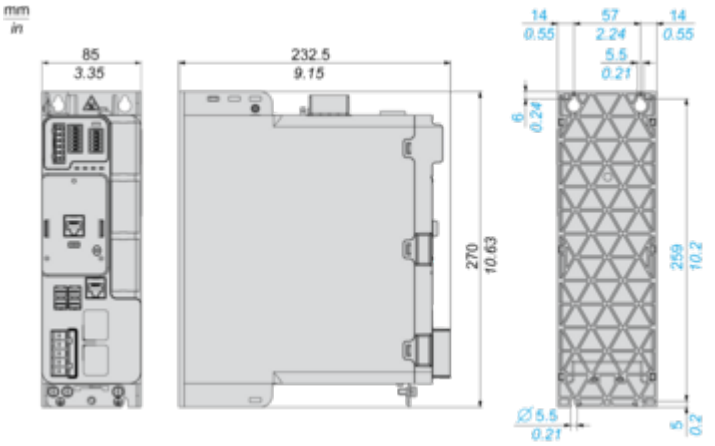
Repack and remanufacture

Recyclability potential, in %	**47**
End of life manual availability	End of Life Information
Take-back	**No**
WEEE Label	**The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins**

Dimensions Drawings

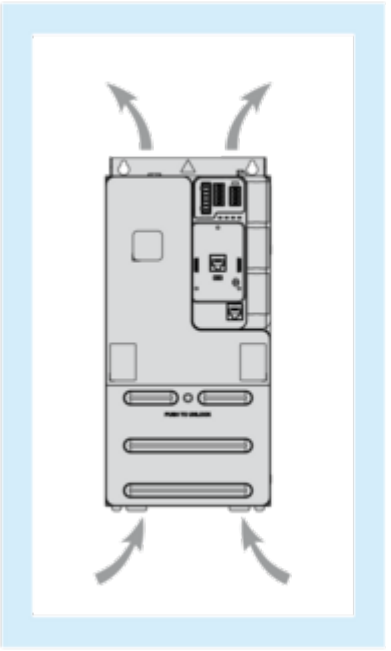
Dimensions

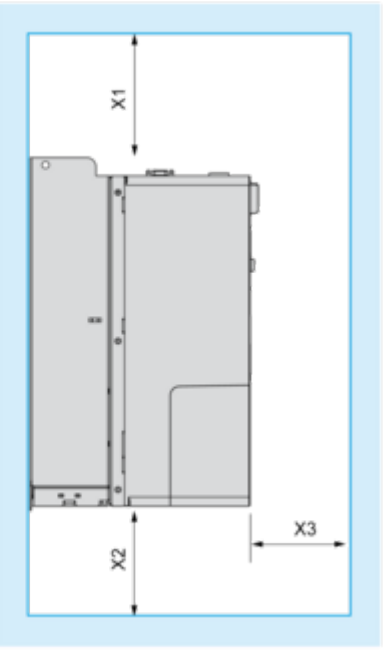
Views: Front - Left - Rear



Mounting and Clearance

Clearance

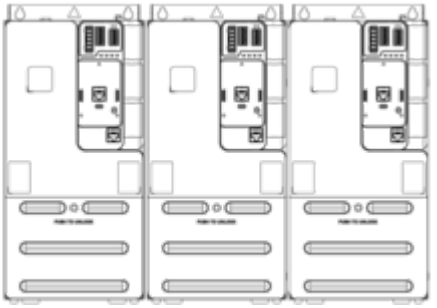




X1	X2	X3			
mm	**in.**	**mm**	**in.**	**mm**	**in.**
≥ 100	≥ 3.94	≥ 100	≥ 3.94	≥ 60	≥ 2.36

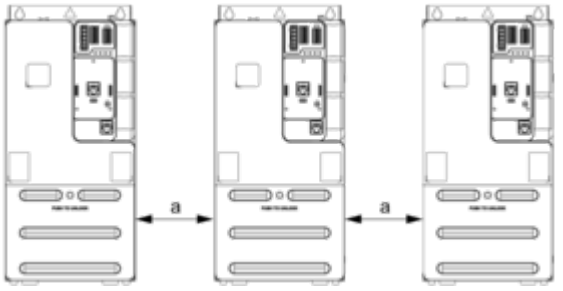
Mounting Types

Mounting Type A: Side by Side IP20



Possible, at ambient temperature ≤ 50 °C (122 °F)

Mounting Type B: Individual IP20

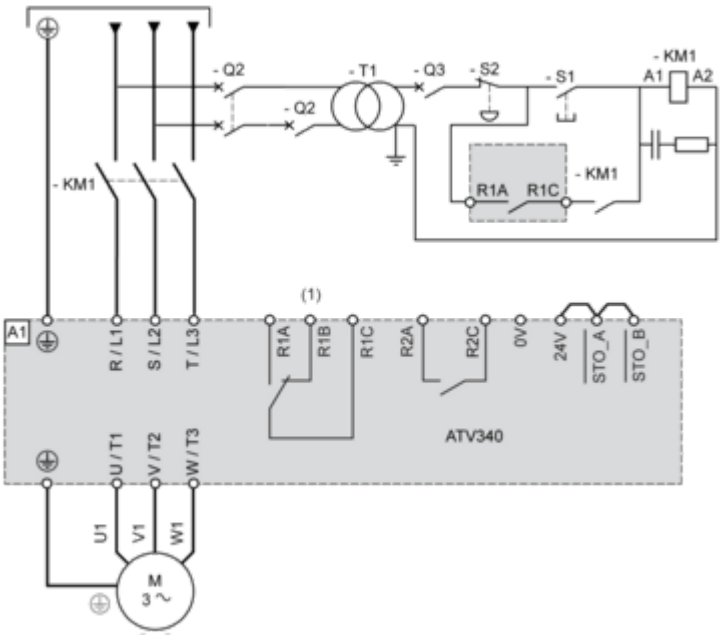


a ≥ 50 mm (1.97 in.) from 50...60°C, no restriction below 50°C

Connections and Schema

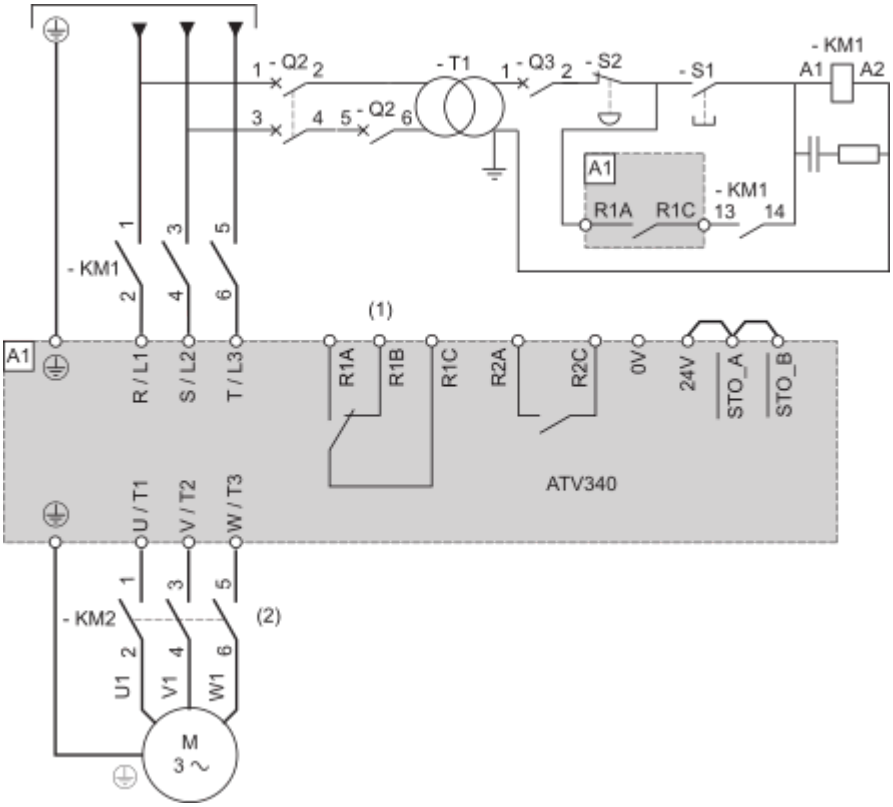
Connections and Schema

Three-phase Power Supply - Diagram With Line Contactor



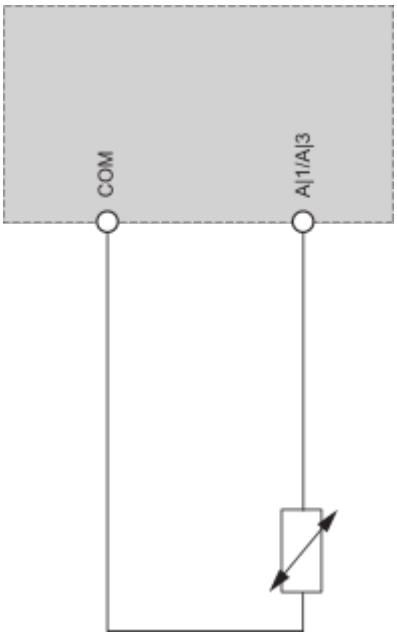
(1) : Use relay output R1 set to operating state Fault to switch Off the product once an error is detected.
NOTE :
• Press S1 until the initialization of the drive is finished.
• An external 24V power supply can be connected so that the control part of the drive is always power supplied.

Three-phase Power Supply - Diagram With Downstream Contactor

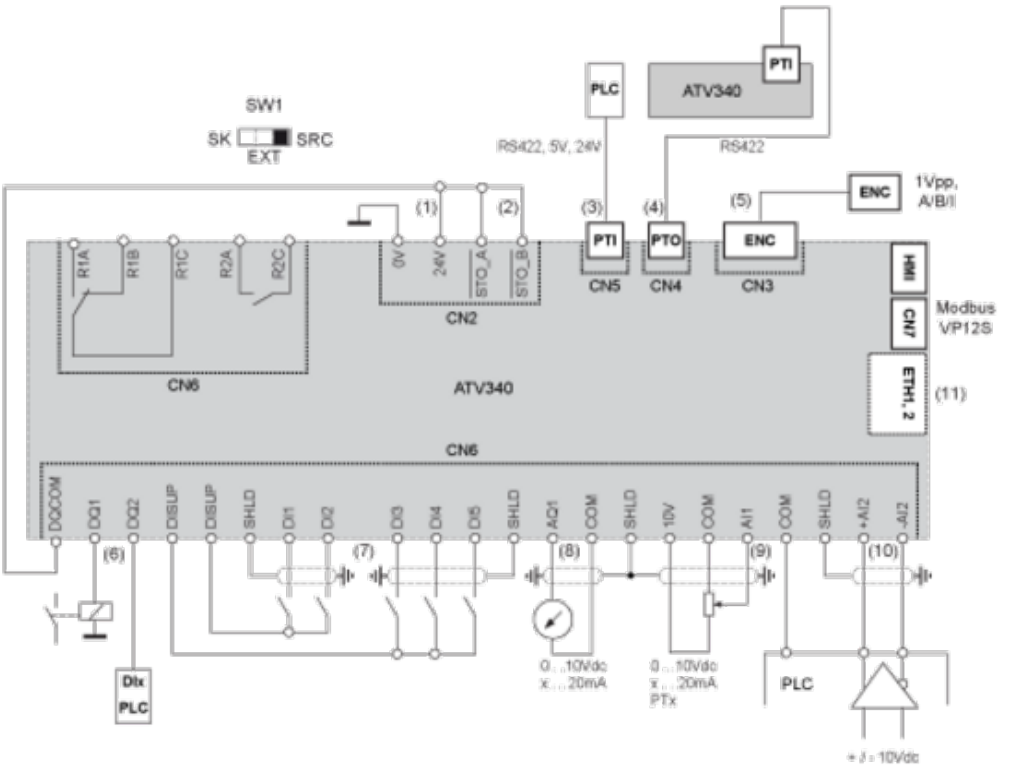


(1) : Use relay output R1 set to operating state Fault to switch Off the product once an error is detected.
(2) : Command of KM2 can be done by using the **[Output contactor cmd]** OCC function. For more information, refer to the programming manual.
NOTE :
• Close upstream contactor, then press S1 after the initialization of the drive is finished.
• An external 24V power supply can be connected so that the control part of the drive is always power supplied.

Sensor Connection



Control Block Wiring Diagram

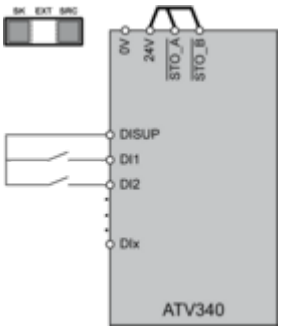


(1) : 24V In, Out, maximum supply current 200 mA is provided,
(2) : STO - Safe Torque Off, see ATV340 Embedded safety function manual NVE64143
(3) : PTI - Pulse Train In, from external source (eg.PLC) Pulse - Direction or A-B signals can be connected
(4) : PTO - Pulse Train Out, can be used to connect to a 2nd ATV340 PTI
(5) : To connect a motor position feedback encoder
(6) : Digital output, e.g. to connect a contactor, also usable as DI
(7) : Digital inputs
(8) : Analog output, e.g. to connect a meter
(9) : Analog input, e.g. from potentiometer
(10) : Differential analog input, e.g. as speed reference from external PLC differential, +/– 10 V
(11) : 2 advanced Ethernet ports ETH1, ETH2 (ATV340•••••E) or 2 Sercos III ports S3P1, S3P2 (ATV340•••••S)

Digital Inputs Wiring

Digital Inputs: Internal Supply

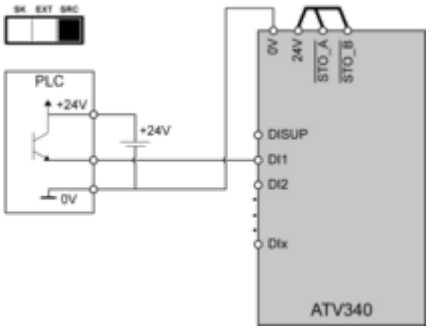
Using DISUP Signal



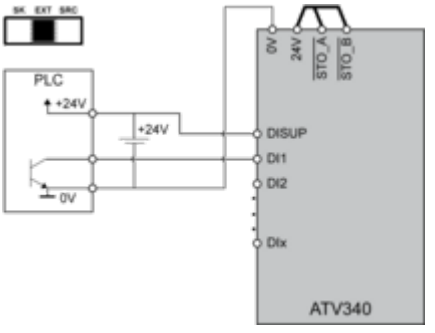
In SRC position DISUP outputs 24 V. In SK position DISUP is connected to 0 V.

Digital Inputs: External Supply

Positive Logic, Source, European Style

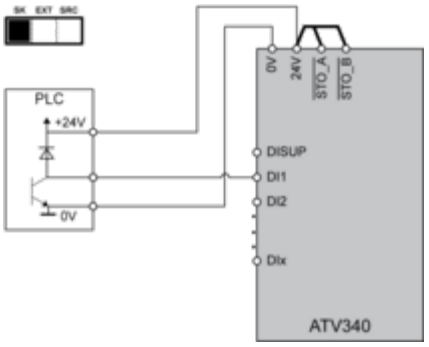


Negative Logic, Sink, Asian Style



Digital Inputs: Internal supply

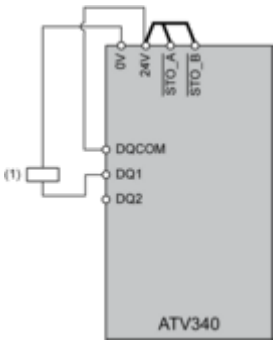
Negative Logic, Sink, Asian Style


SK EXT SRC
PLC
+24V
0V
0V
24V
STO_A
STO_B
DISUP
DI1
DI2
DIx
ATV340

Digital Outputs Wiring

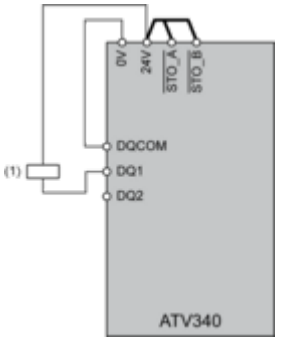
Digital Outputs: Internal Supply

Positive Logic, Source, European Style, DQCOM to +24V



(1) Relay or valve

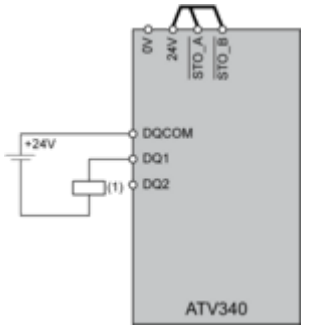
Negative Logic, Sink, Asian Style, DQCOM to 0V



(1) Relay or valve

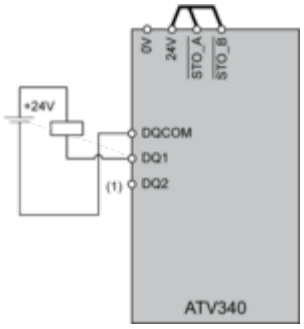
Digital Outputs: External Supply

Positive Logic, Source, European Style, DQCOM to +24V



(1) Relay or valve

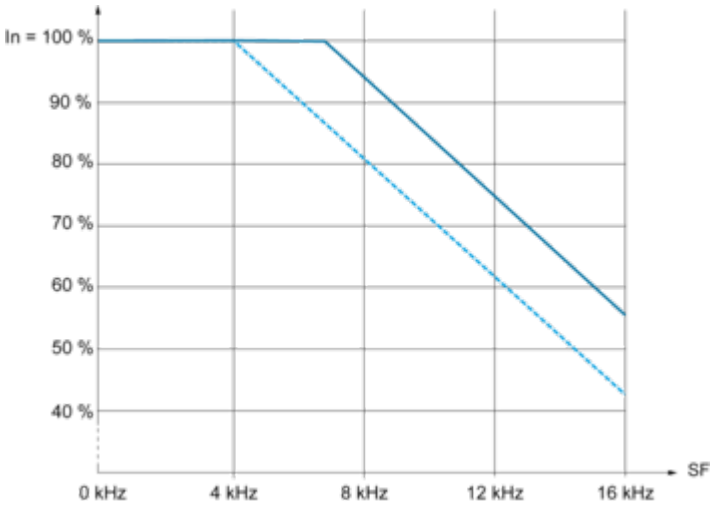
Negative Logic, Sink, Asian Style, DQCOM to 0V



(1) Relay or valve

Performance Curves

Derating Curves



40 °C (104 °F) - Mounting type A and B
50 °C (122 °F) - Mounting type A and B
In : Nominal Drive Current
SF : Switching Frequency

Technical Illustration

Dimensions

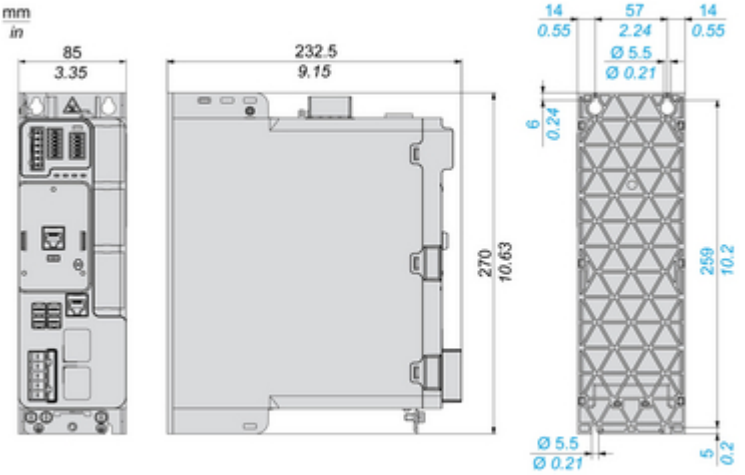


Image of product in real life situation

